Carnegie Mellon University

Database Systems

Distributed OLTP Databases



ADMINISTRIVIA

No Class on Thursday Nov 27th

DBMS Potpourri Lecture on Wednesday Dec 4th

Project #4 is due Sunday Dec 8th @ 11:59pm

Homework #6 is due Monday Dec 9th @ 11:59pm

Final Exam is on Friday Dec 13th @ 8:30am

- \rightarrow Early exam will <u>not</u> be offered.
- \rightarrow Do <u>not</u> get locked up in jail before this date.



UPCOMING DATABASE TALKS

GreptimeDB (DB Seminar)

- → Monday Nov 25th @ 4:30pm
- \rightarrow Zoom



OpenDAL / DataBend (DB Seminar)

- → Monday Nov 25th @ 4:30pm
- \rightarrow Zoom





LAST CLASS

System Architectures

→ Shared-Everything, Shared-Disk, Shared-Nothing

Partitioning/Sharding

→ Hash, Range, Round Robin

Transaction Coordination

→ Centralized vs. Decentralized



OLTP VS. OLAP

On-line Transaction Processing (OLTP):

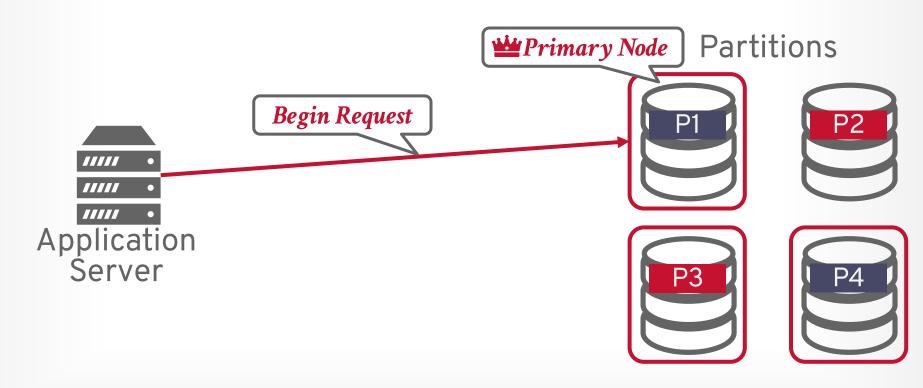
- \rightarrow Short-lived read/write txns.
- → Small footprint.
- \rightarrow Repetitive operations.

On-line Analytical Processing (OLAP):

- \rightarrow Long-running, read-only queries.
- \rightarrow Complex joins.
- \rightarrow Exploratory queries.

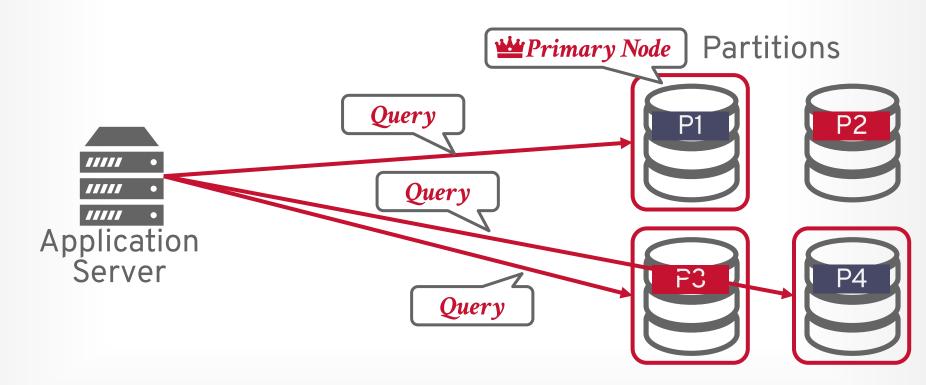


DECENTRALIZED COORDINATOR



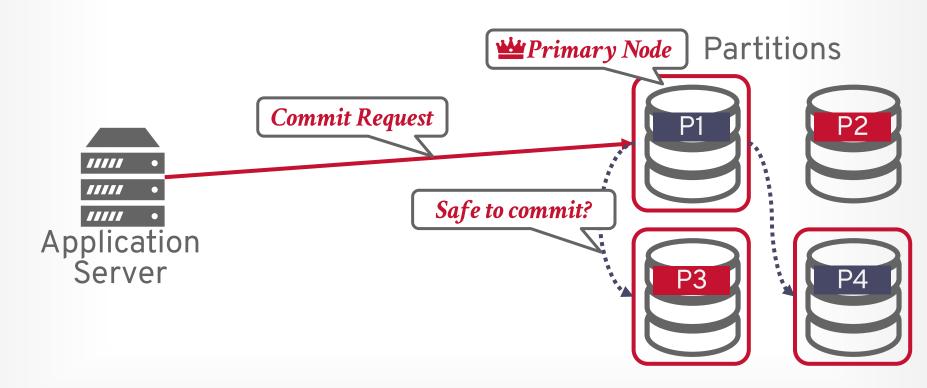


DECENTRALIZED COORDINATOR





DECENTRALIZED COORDINATOR





OBSERVATION

Recall that our goal is to have multiple physical nodes appear as a single logical DBMS.

We have not discussed how to ensure that all nodes agree to commit a txn and then to make sure it does commit if the DBMS decides it should.

- \rightarrow What happens if a node fails?
- → What happens if messages show up late?
- → What happens if the system does not wait for every node to agree to commit?



IMPORTANT ASSUMPTION

We will assume that all nodes in a distributed DBMS are well-behaved and under the same administrative domain.

→ If we tell a node to commit a txn, then it will commit the txn (if there is not a failure).



If you do <u>not</u> trust the other nodes in a distributed DBMS, then you need to use a <u>Byzantine Fault</u> <u>Tolerant</u> protocol for txns (blockchain).

→ Blockchains are **not** good for high-throughput workloads.



TODAY'S AGENDA

Replication
Atomic Commit Protocols
Consistency Issues (CAP / PACELC)



REPLICATION

The DBMS can replicate a database across redundant nodes to increase availability.

- → Partitioned vs. Non-Partitioned
- → Shared-Nothing vs. Shared-Disk

Design Decisions:

- → Replica Configuration
- → Propagation Scheme
- → Propagation Timing
- → Update Method



REPLICA CONFIGURATIONS

Approach #1: Primary-Replica

- → All updates go to a designated primary for each object.
- → The primary propagates updates to its replicas by shipping logs.
- → Read-only txns may be allowed to access replicas.
- → If the primary goes down, then hold an election to select a new primary.

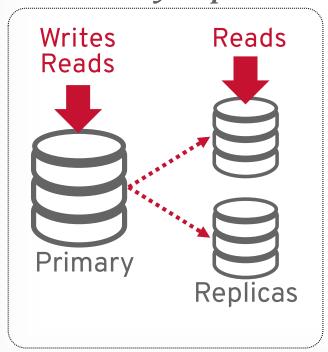
Approach #2: Multi-Primary

- → Txns can update data objects at any replica.
- → Replicas <u>must</u> synchronize with each other using an atomic commit protocol.

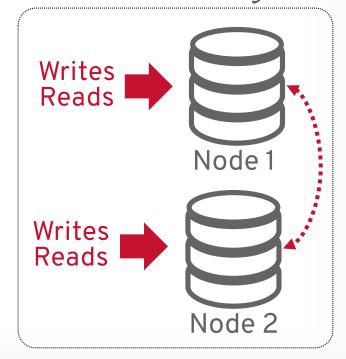


REPLICA CONFIGURATIONS

Primary-Replica



Multi-Primary





K-SAFETY

K-safety is a threshold for determining the fault tolerance of the replicated database.

The value *K* represents the number of replicas per data object that must always be available.

If the number of replicas goes <u>below</u> this threshold, then the DBMS halts execution and takes itself offline.



When a txn commits on a replicated database, the DBMS decides whether it must wait for that txn's changes to propagate to other nodes before it can send the acknowledgement to application.

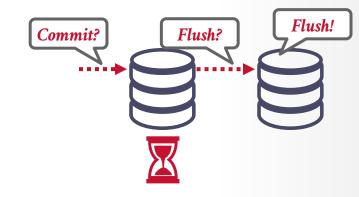
Propagation levels:

- → Synchronous (*Strong Consistency*)
- → Asynchronous (*Eventual Consistency*)



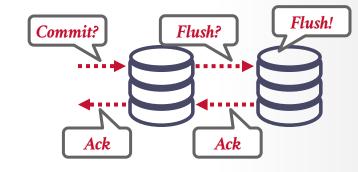
Approach #1: Synchronous

→ The primary sends updates to replicas and then waits for them to acknowledge that they fully applied (i.e., logged) the changes.



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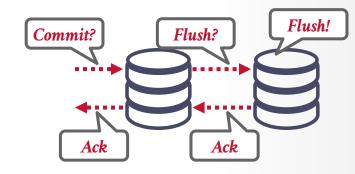


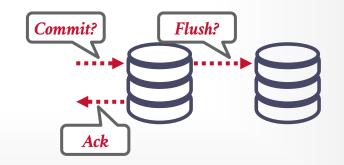
Approach #1: Synchronous

→ The primary sends updates to replicas and then waits for them to acknowledge that they fully applied (i.e., logged) the changes.

Approach #2: Asynchronous

→ The primary immediately returns the acknowledgement to the client without waiting for replicas to apply the changes.







PROPAGATION TIMING

Approach #1: Continuous

- → The DBMS sends log messages immediately as it generates them.
- → Also need to send a commit/abort message.

Approach #2: On Commit

- → The DBMS only sends the log messages for a txn to the replicas once the txn is commits.
- \rightarrow Do not waste time sending log records for aborted txns.



ACTIVE VS. PASSIVE

Approach #1: Active-Active

- \rightarrow A txn executes at each replica independently.
- → Need to check at the end whether the txn ends up with the same result at each replica.

Approach #2: Active-Passive

- → Each txn executes at a single location and propagates the changes to the replica.
- → Can either do physical or logical replication.
- → Not the same as Primary-Replica vs. Multi-Primary



OBSERVATION

If only one node decides whether a txn is allowed to commit, then making that decision is easy.

Life is <u>much</u> harder when multiple nodes are allowed to decide:

- → What if multiple nodes need to agree a txn is allowed to commit?
- → What if a primary node goes down and the system needs to choose a new primary?



ATOMIC COMMIT PROTOCOL

Coordinating the commit order of txns across nodes in a distributed DBMS.

- → Commit Order = State Machine
- → It does <u>not</u> matter whether the database's contents are replicated or partitioned.

Examples:

- → Two-Phase Commit (1970s)
- → Three-Phase Commit (1983)
- → <u>Viewstamped Replication</u> (1988)
- \rightarrow Paxos (1989)
- \rightarrow ZAB (2008?)
- → <u>Raft</u> (2013)



ATOMIC COMMIT PROTOCOL

Resource Managers (RMs)

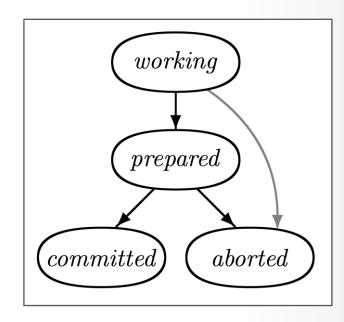
- → Execute on different nodes
- \rightarrow Coordinate to decide fate of a txn.

Properties of the Commit Protocol

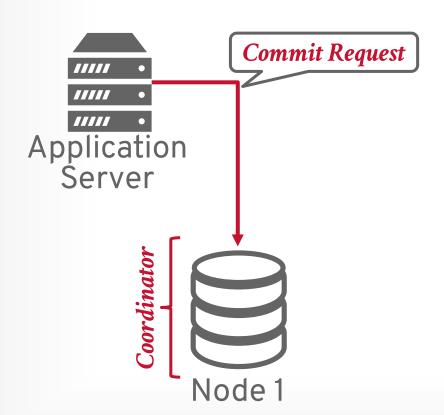
- → **Stability**: Once the fate is decided, it cannot be changed.
- → **Consistency**: All RMs end up in the same state.

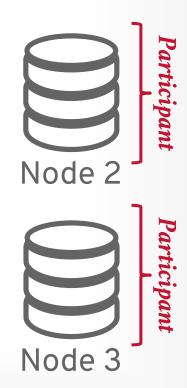
Assumes Liveness:

- → There is some way of progressing forward
- → Enough nodes are alive and connected for the duration of the protocol.

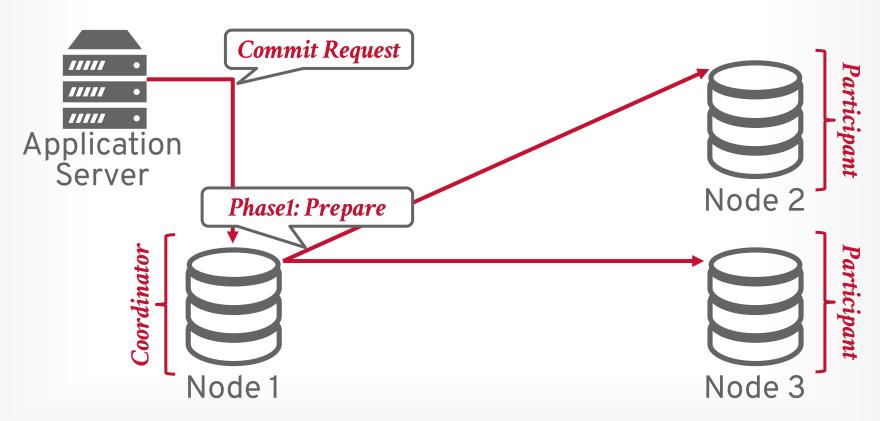


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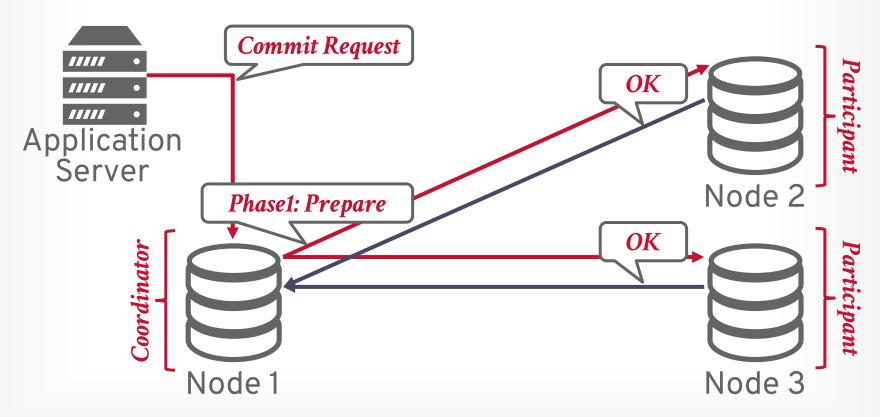




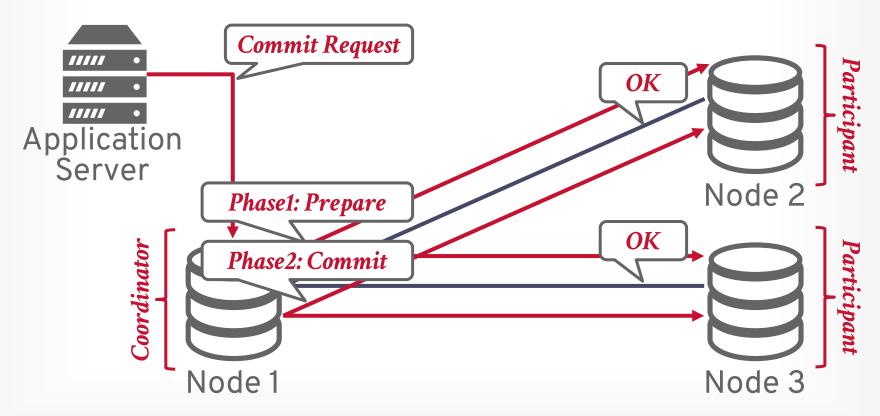




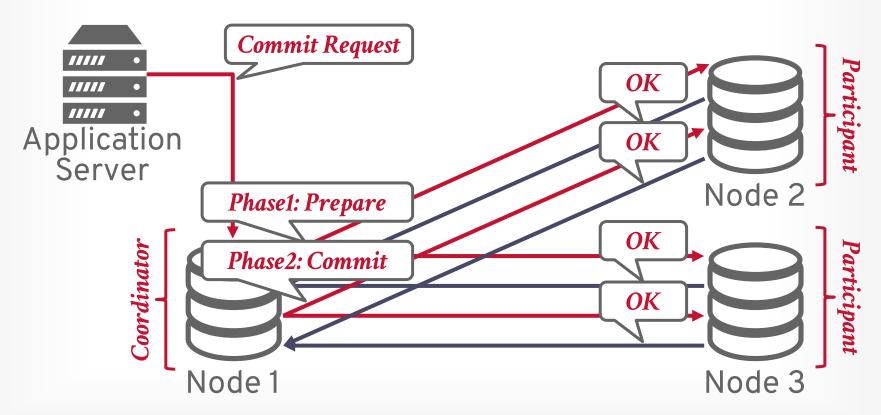




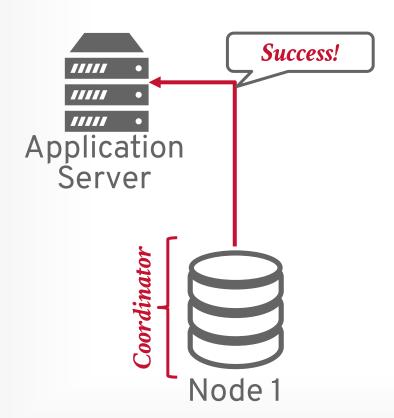


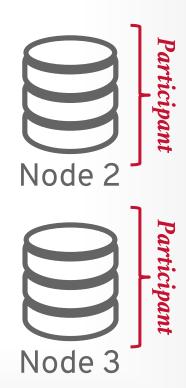




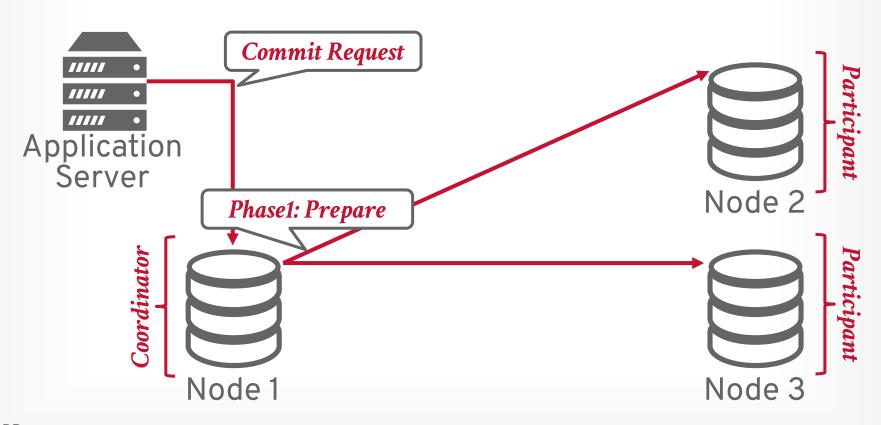




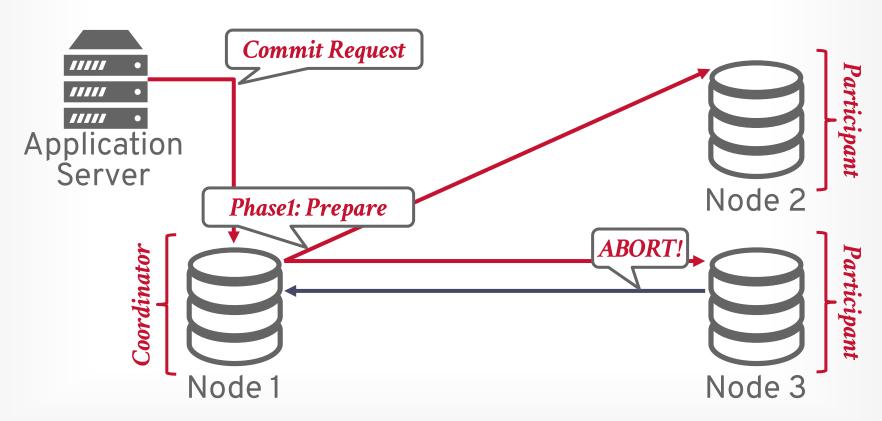




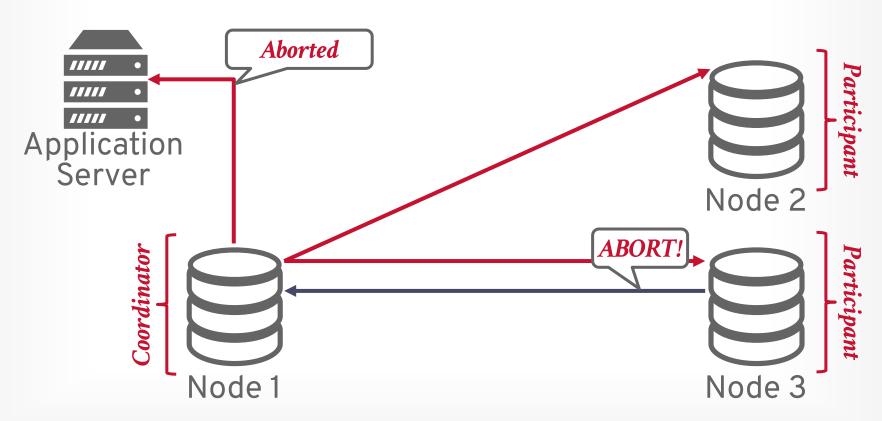




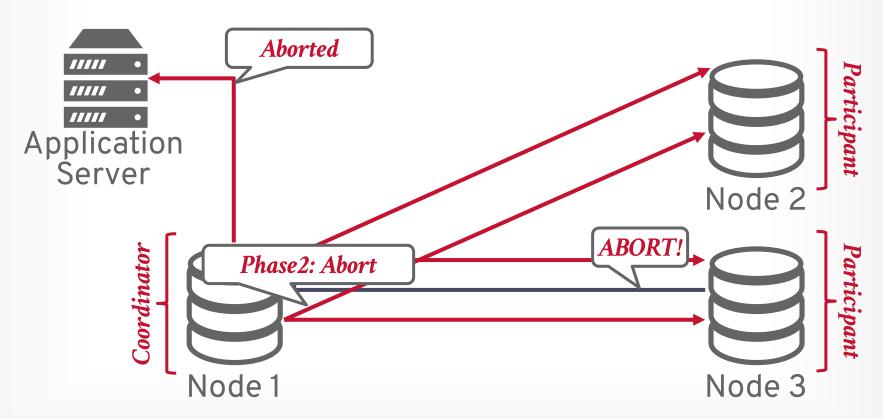




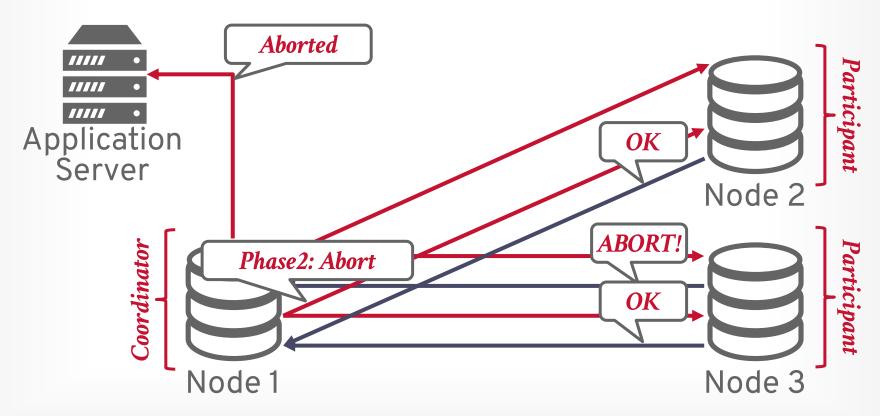














TWO-PHASE COMMIT

Each node records the inbound/outbound messages and outcome of each phase in a non-volatile storage log.

On recovery, examine the log for 2PC messages:

- \rightarrow If local txn in prepared state, contact coordinator.
- \rightarrow If local txn <u>not</u> in prepared, abort it.
- → If local txn was committing and node is the coordinator, send **COMMIT** message to nodes.



TWO-PHASE COMMIT FAILURES

What happens if coordinator crashes?

- → Participants must decide what to do after a timeout.
- \rightarrow System is <u>not</u> available during this time.

What happens if participant crashes?

- → Coordinator assumes that it responded with an abort if it has <u>not</u> sent an acknowledgement yet.
- → Again, nodes use a timeout to determine whether a participant is dead.



2PC OPTIMIZATIONS

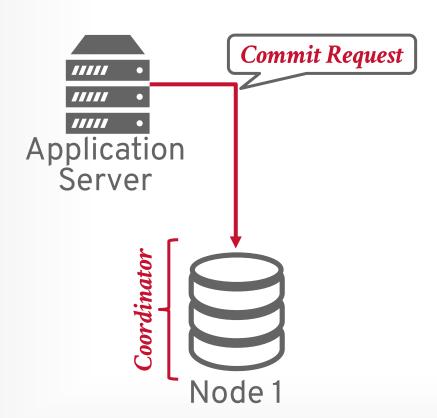
Early Prepare Voting (Rare)

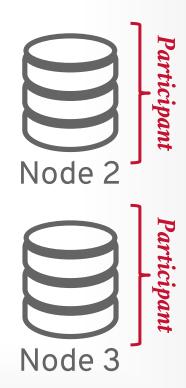
→ If you send a query to a remote node that you know will be the last one to execute in this txn, then that node will also return their vote for the prepare phase with the query result.

Early Ack After Prepare (Common)

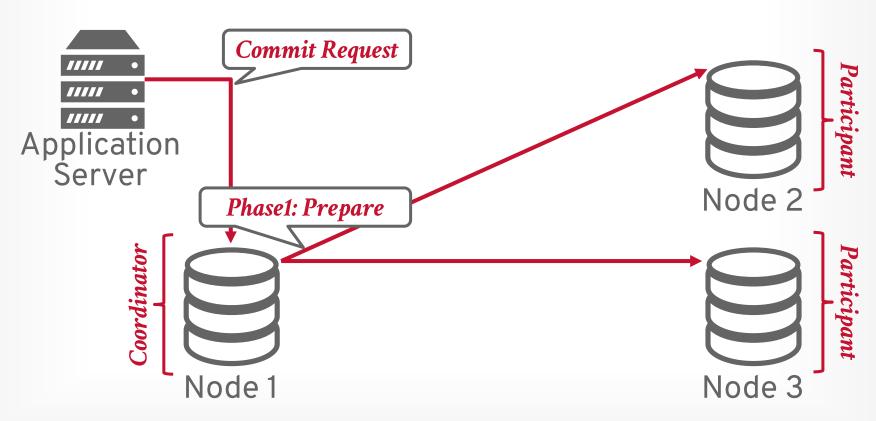
→ If all nodes vote to commit a txn, the coordinator can send the client an acknowledgement that their txn was successful before the commit phase finishes.



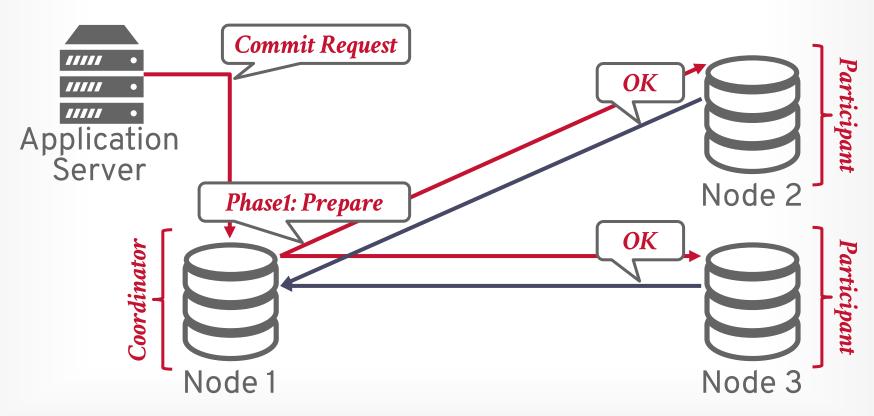




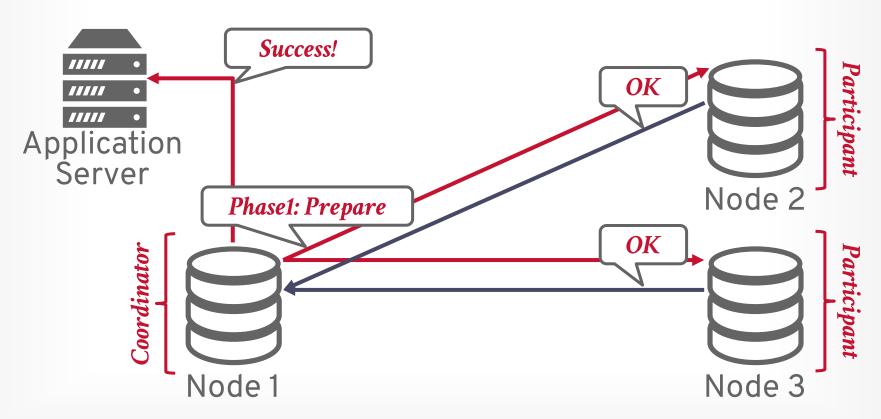




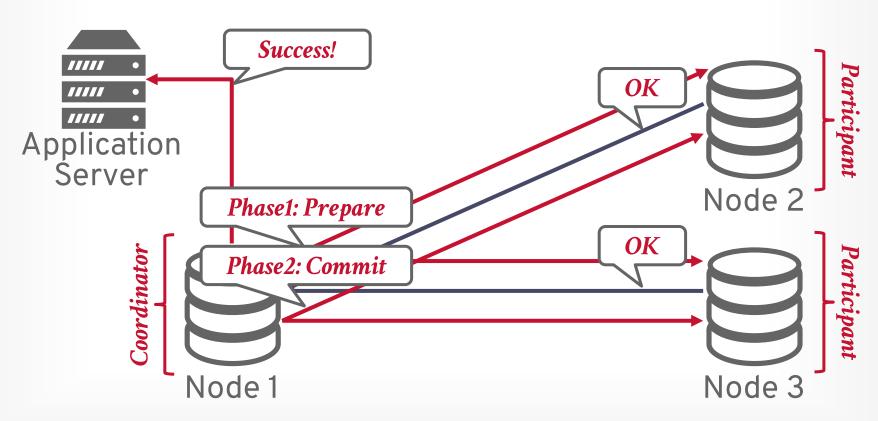




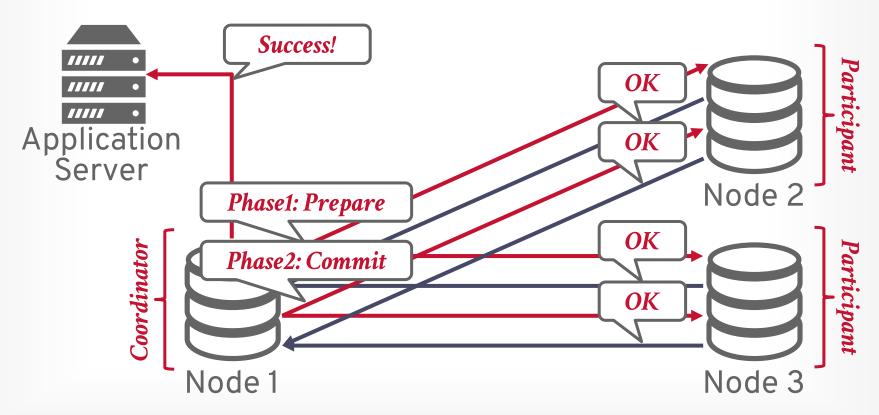














Consensus protocol where a coordinator proposes an outcome (e.g., commit or abort) and then the participants vote on whether that outcome should succeed.

Does not block if a <u>majority</u> of participants are available and has provably minimal message delays in the best case.

The Part-Time Parliament

LESLIE LAMPORT

Digital Equipment Corporation

Recent archaeological discoveries on the island of Paxos reveal that the parliament functioned despite the peripatetic propensity of its part-time legislators. The legislators maintained consistent copies of the parliamentary record, despite their frequent forays from the chamber and the forgetfulness of their messengers. The Paxon parliament's protocol provides a new way of implementing the state-machine approach to the design of distributed systems.

Categories and Subject Descriptors: C2.4 [Computer-Communications Networks]: Distributed Systems—Network operating systems, D4.5 [Operating Systems]: Reliability—Fault-tolerance; J.1 [Administrative Data Processing]: Government

General Terms: Design, Reliability

Additional Key Words and Phrases: State machines, three-phase commit, voting

This submission was recently discovered behind a filing cabinet in the TOCS editorial office. Despite its age, the editor-in-chief felt that it was worth publishing. Because the author is currently doing field work in the Greek isless and cannot be reached, I was asked to prepare it for publication.

The author appears to be an archeologist with only a passing interest in computer science. This is unfortunate even though the obscure ancient Paxon ovilization be describes is of little interest to most computer scientists, its legislative system is an excellent model for how to implement a distributed computer system in an asymchronous environment. Indeed, some of the refinements the Paxons made to their protocol appear to be unknown in the systems literature.

The author does give a brief discussion of the Paxon Parliament's relevance to distributed computing in Section 4. Computer scientists will probably want to read that section first. Even before that, they might want to read the explanation of the algorithm for computer scientists by Lampon [1996]. The algorithm is also described more formally by De Prisco et al. [1997]. I have added further comments on the relation between the ancient protocols and more recent work at the end of Section 4.

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Consensus protocol where a coordinator proposes an outcome (e.g., commit or abort) and then t participants vote on whether that outcome should succeed.

Does not block if a majority of participants are available and has provably minimal message delays the best case.

Consensus on Transaction Commit

JIM GRAY and LESLIE LAMPORT Microsoft Research

 $The \ distributed \ transaction \ commit \ problem \ requires \ reaching \ agreement \ on \ whether \ a \ transaction$ in committed or aborted. The classic Two-Phase Commit protocol blocks if the coordinator fails. Fault-tolerant consensus algorithms also reach agreement, but do not block whenever any majority of the processes are working. The Paxos Commit algorithm runs a Paxos consensus algorithm on the commit/abort decision of each participant to obtain a transaction commit protocol that uses 2F+1coordinators and makes progress if at least F+1 of them are working properly. Paxos Commit has the same stable-storage write delay, and can be implemented to have the same message delay in the fault-free case as Two-Phase Commit, but it uses more messages. The classic Two-Phase as the interpretation of the special F=0 case of the Paxos Commit algorithm is obtained as the special F=0 case of the Paxos Commit algorithm.

Categories and Subject Descriptors: D.4.1 [Operating Systems]: Process Management—Con-Carency; D.4.5 (Operating Systems): Reliability—Rault-tolerance; D.4.7 (Operating Systems): General Terms: Algorithms, Reliability

Additional Key Words and Phrases: Consensus, Paxos, two-phase commit

1. INTRODUCTION

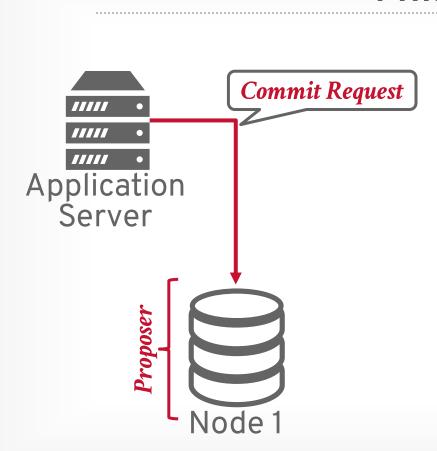
tiple sites, terminated by a request to commit or abort the transaction. The sites then use a transaction commit protocol to decide whether the transaction is committed or aborted. The transaction can be committed only if all sites are willing to commit it. Achieving this all-or-nothing atomicity property in a distributed system is not trivial. The requirements for transaction commit are

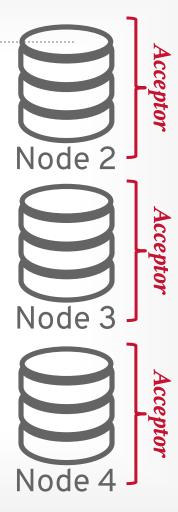
The classic transaction commit protocol is Two-Phase Commit [Gray 1978], described in Section 3. It uses a single coordinator to reach agreement. The failure of that coordinator can cause the protocol to block, with no process knowing the outcome, until the coordinator is repaired. In Section 4, we use the Paxos consensus algorithm [Lamport 1998] to obtain a transaction commit protocol

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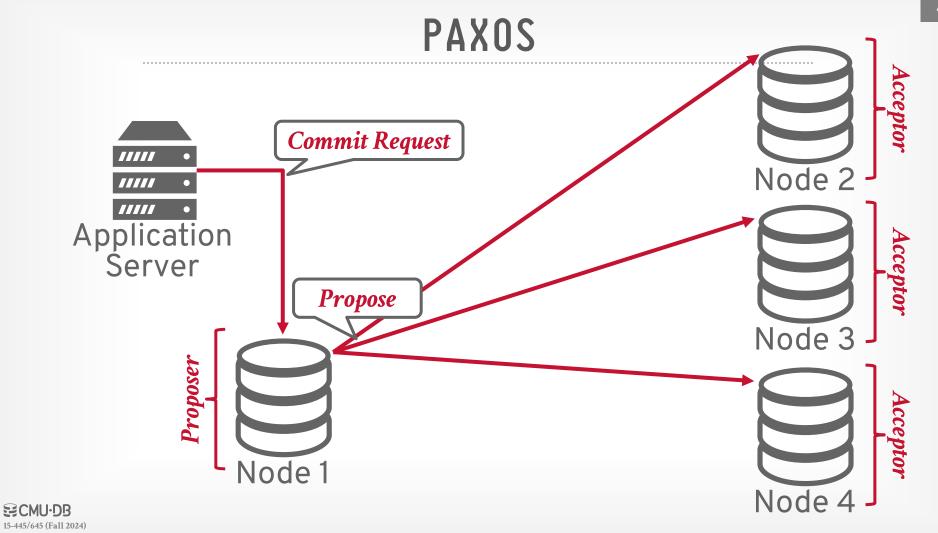
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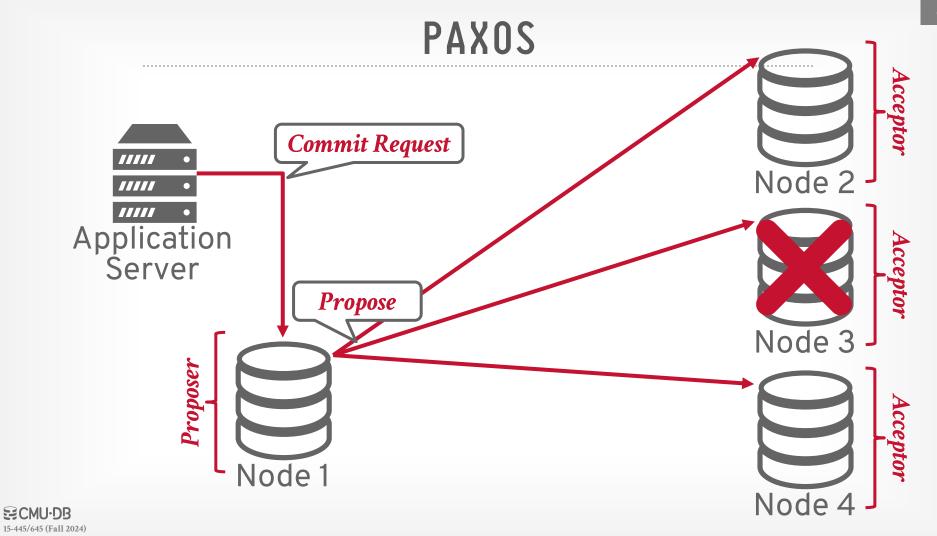
ACM Transactions on Database Systems, Vol. 31, No. 1, March 2006, Pages 133-160.

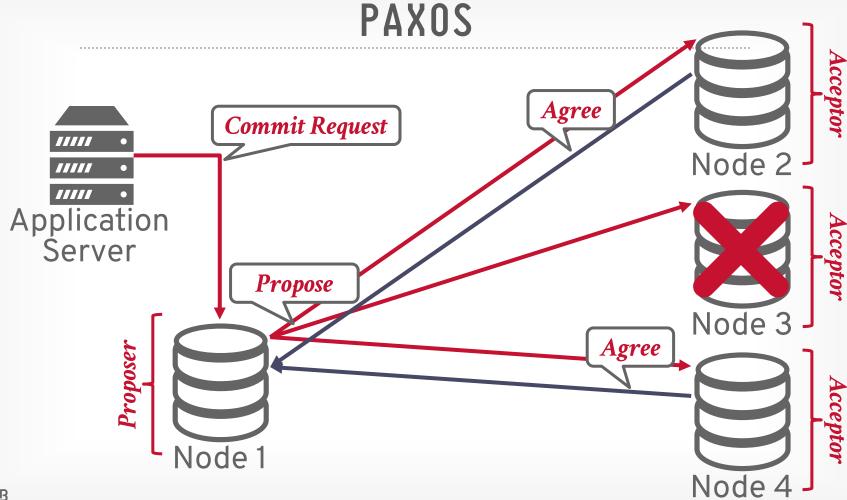




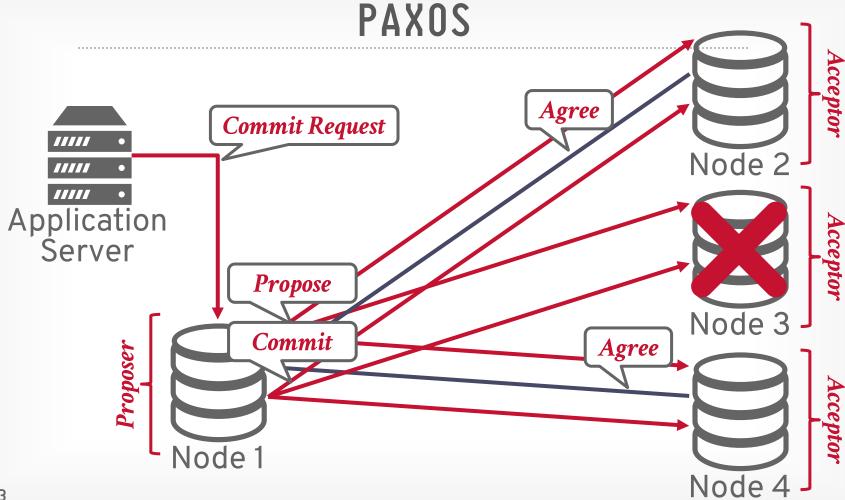




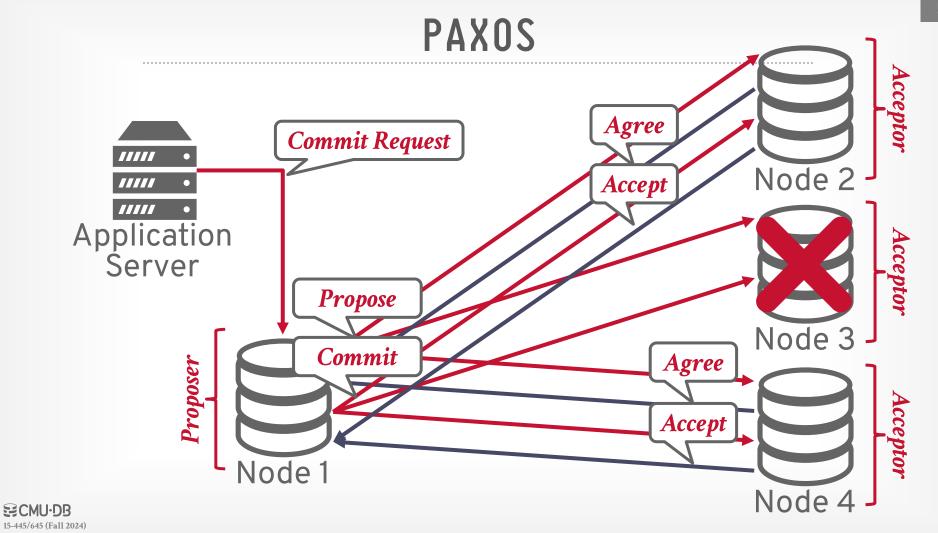


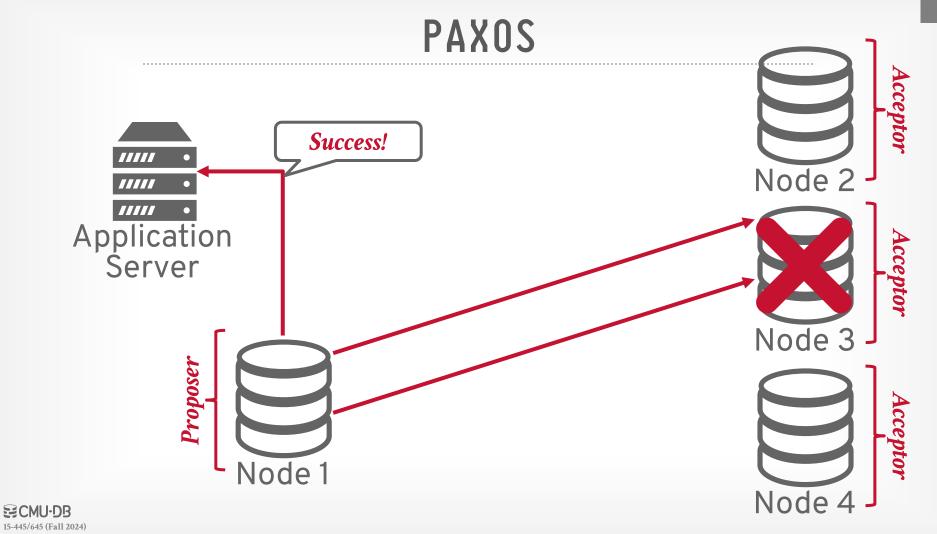


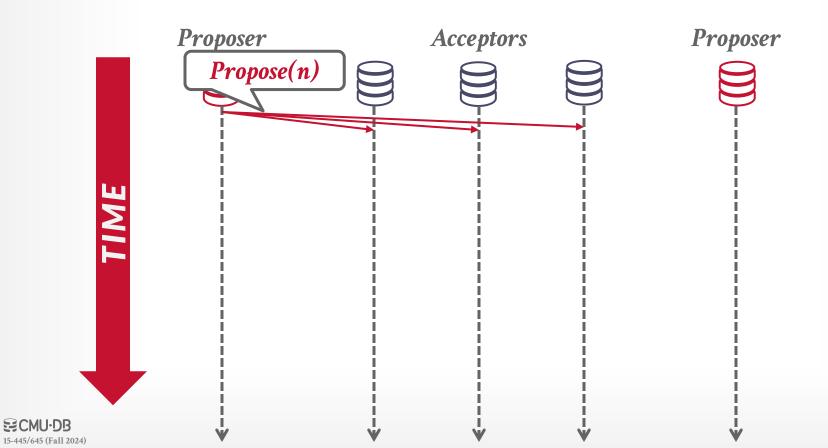


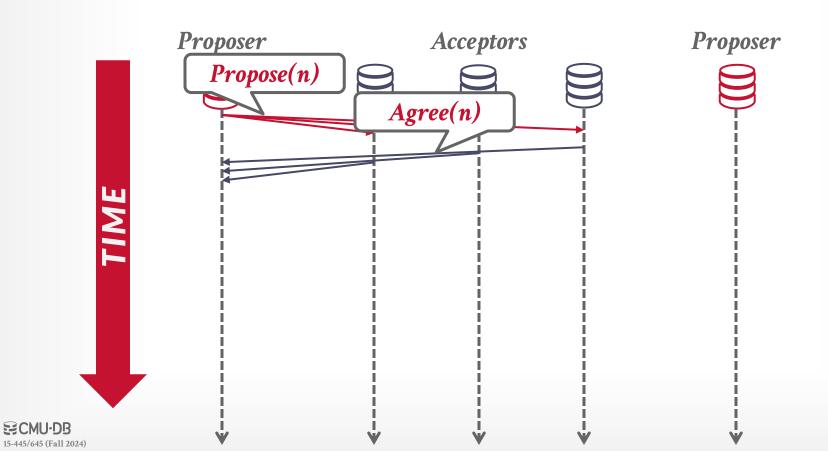


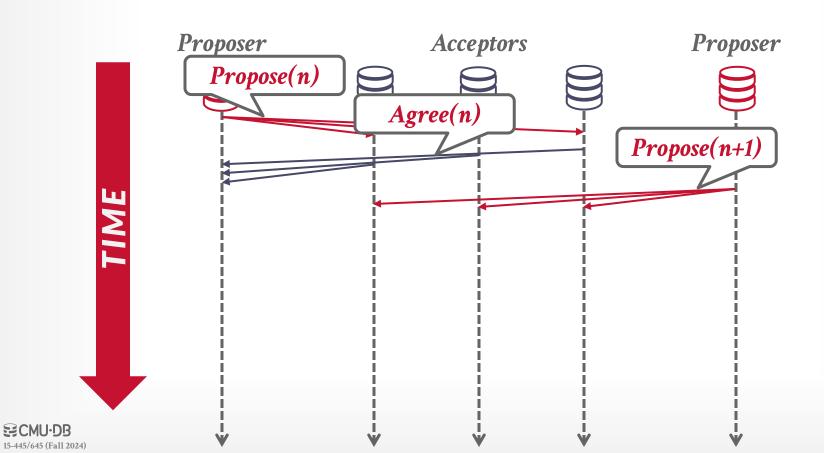


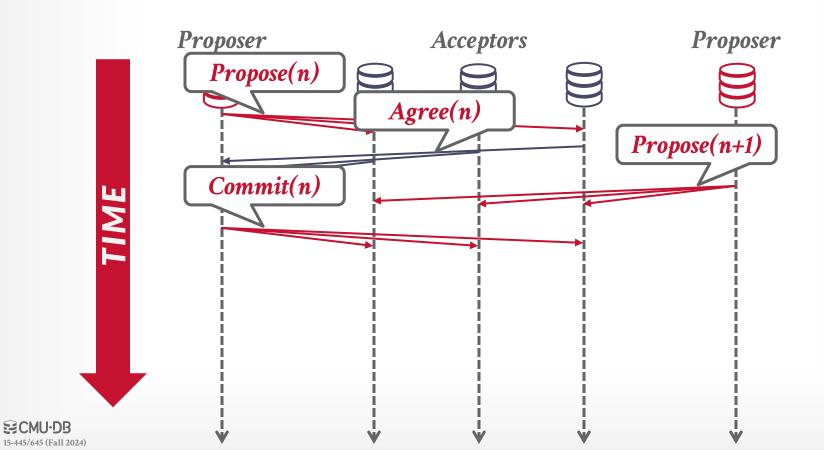


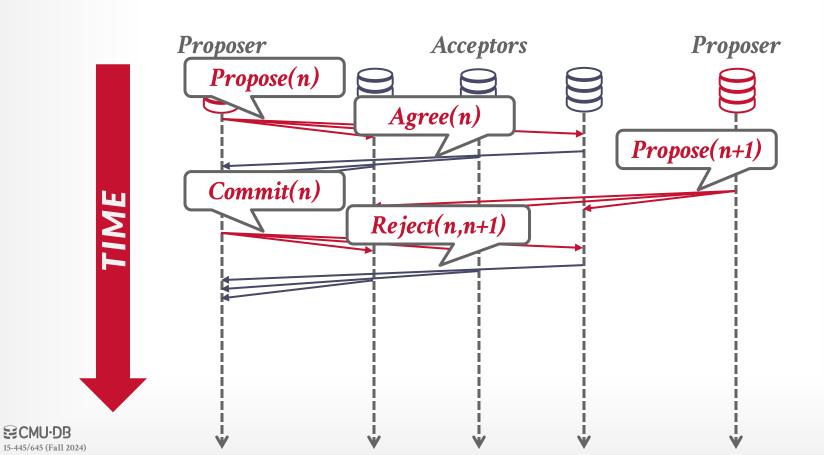


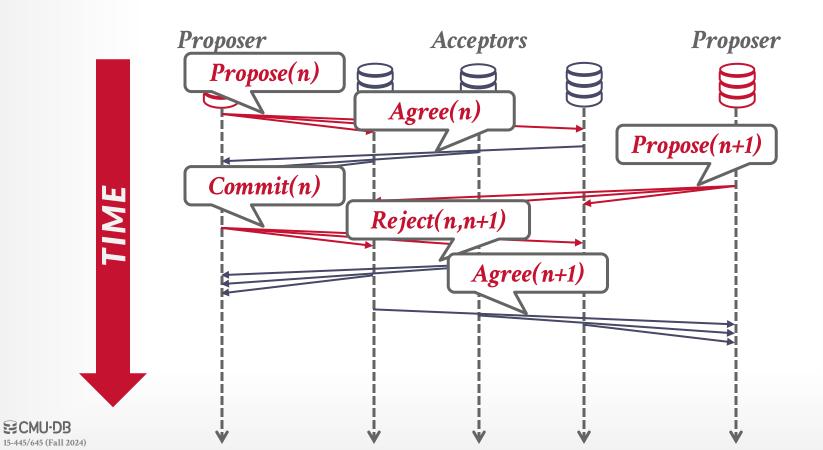


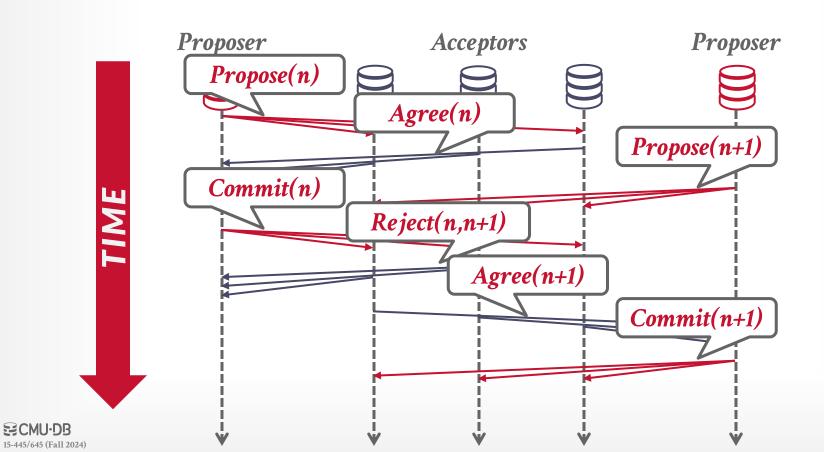


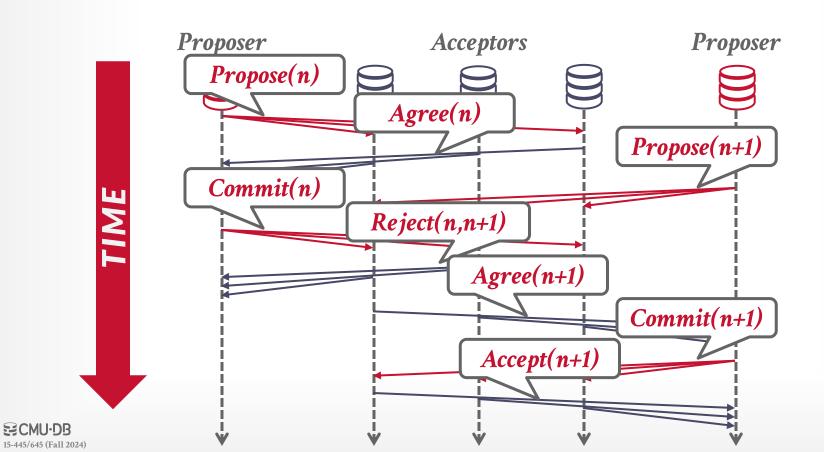












MULTI-PAXOS

If the system elects a single leader that oversees proposing changes for some period, then it can skip the **Propose** phase.

→ Fall back to full Paxos whenever there is a failure.

The system periodically renews the leader (known as a *lease*) using another Paxos round.

→ Nodes must exchange log entries during leader election to make sure that everyone is up-to-date.



2PC VS. PAXOS VS. RAFT

Two-Phase Commit

→ Blocks if coordinator fails after the prepare message is sent, until coordinator recovers.

Paxos

→ Non-blocking if a majority participants are alive, provided there is a sufficiently long period without further failures.

Raft:

- \rightarrow Similar to Paxos but with fewer node types.
- \rightarrow Only nodes with most up-to-date log can become leaders.



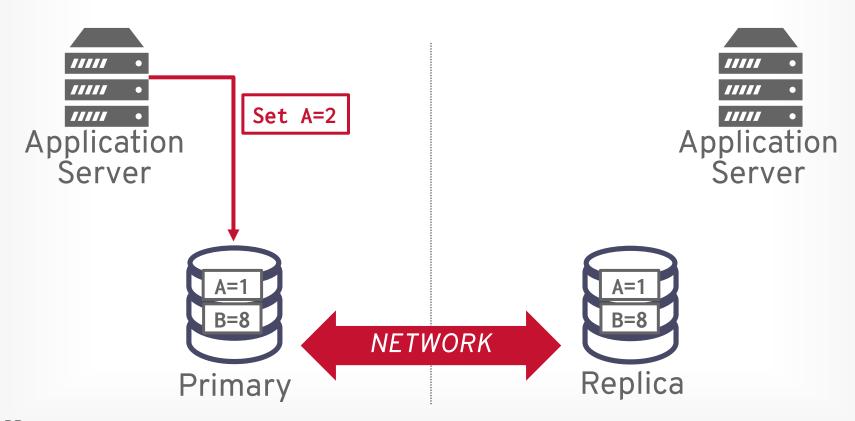
CAP THEOREM

Proposed in the late 1990s that is impossible for a distributed database to always be:

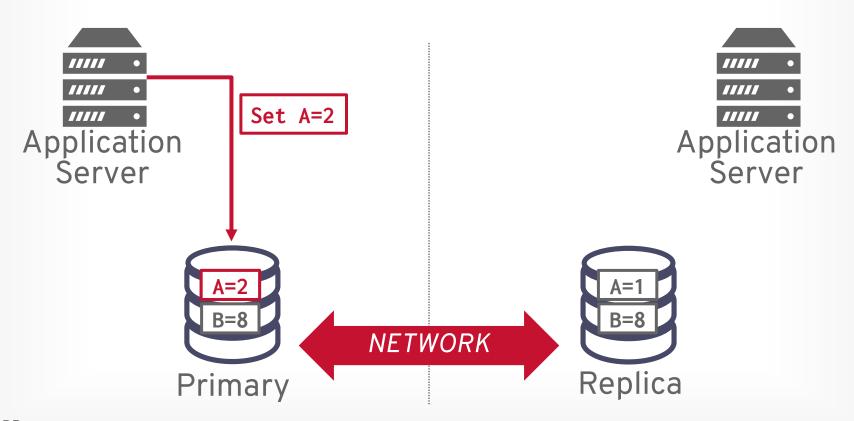
- → Consistent
- \rightarrow **A**lways Available
- \rightarrow Network Partition Tolerant

Whether a DBMS provides **C**onsistency or **A**vailability during a **N**etwork partition.

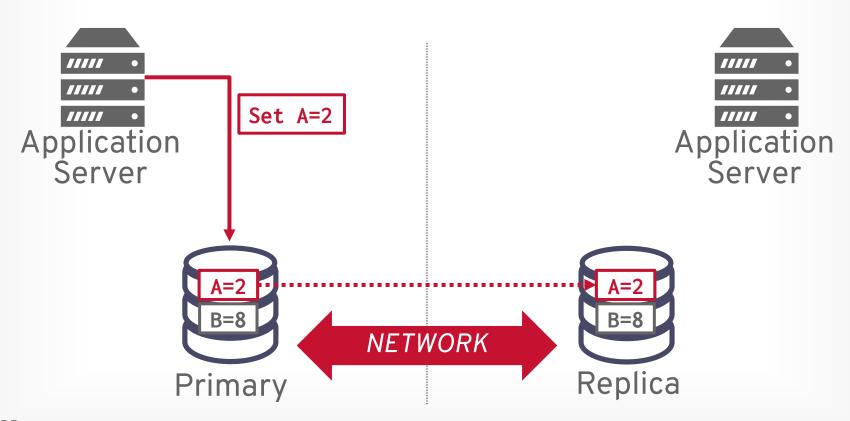




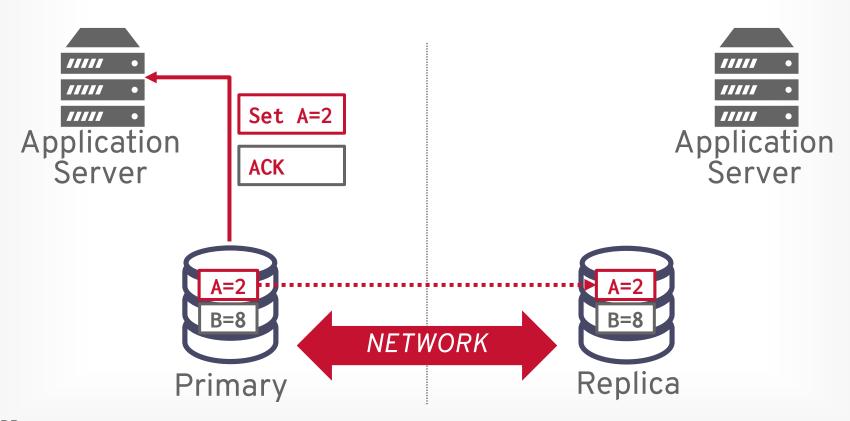




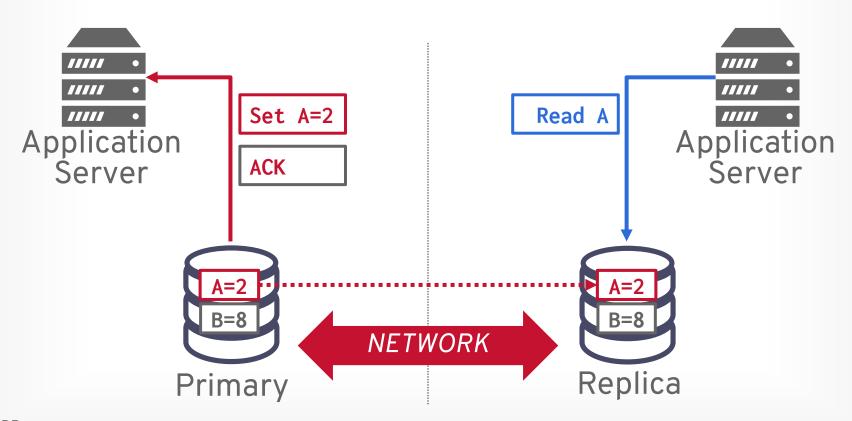




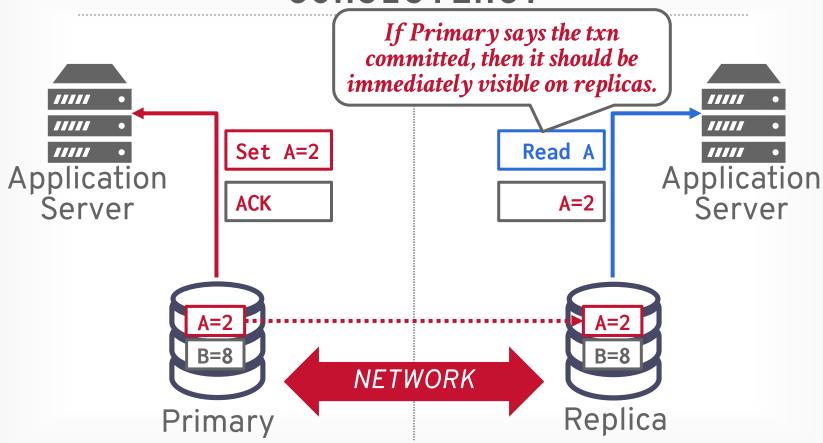






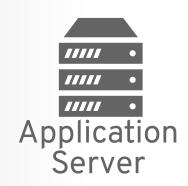


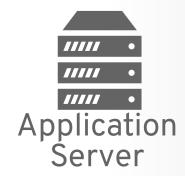






AVAILABILITY









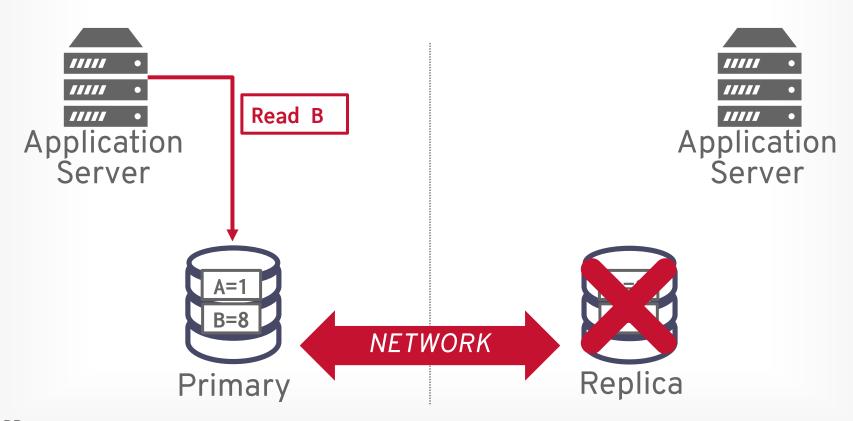
AVAILABILITY



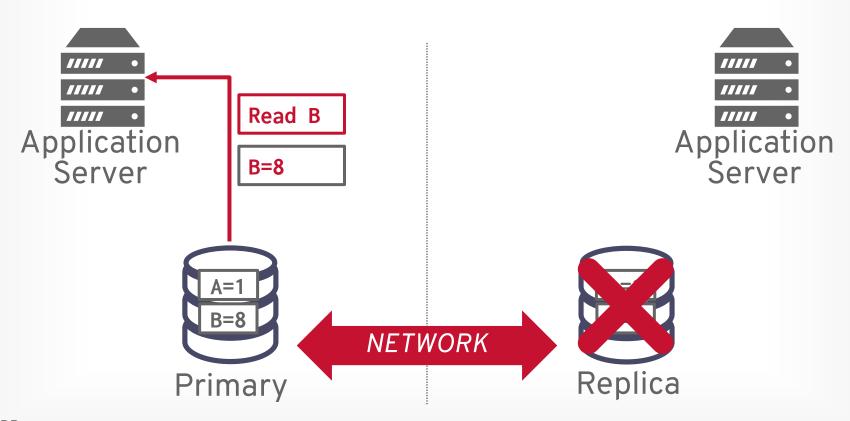




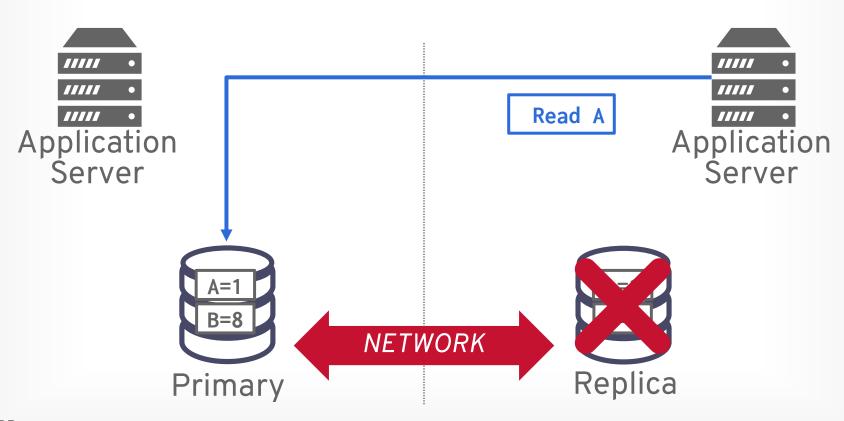




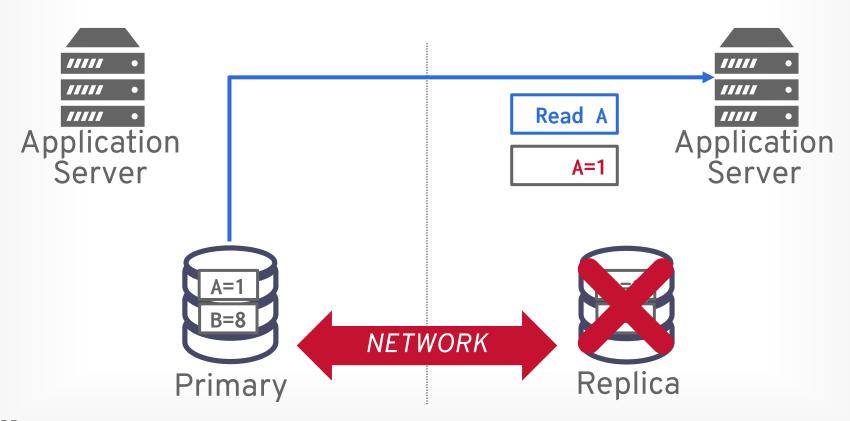




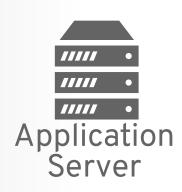












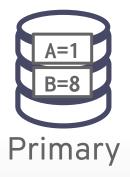




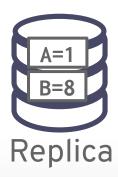








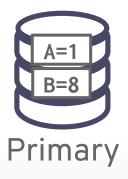








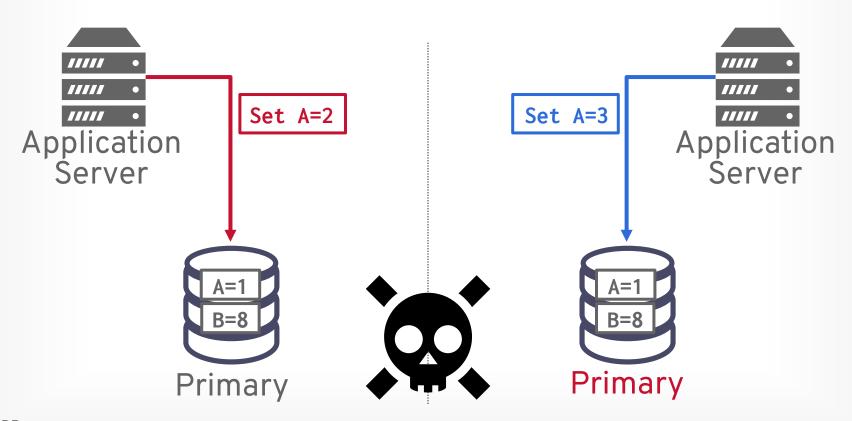




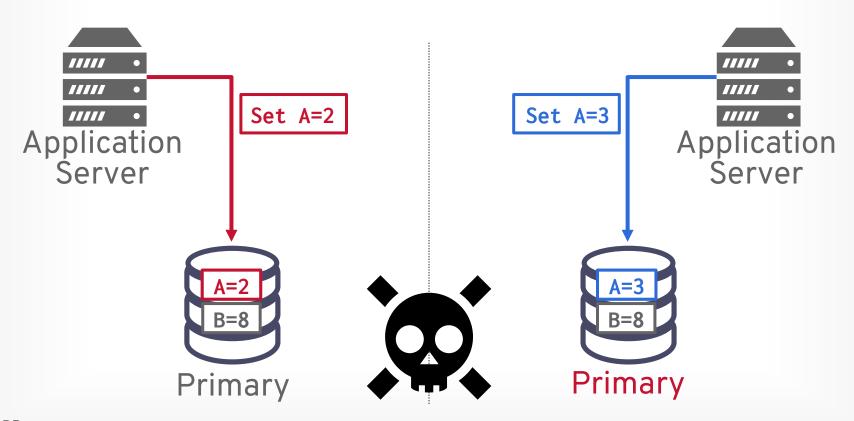




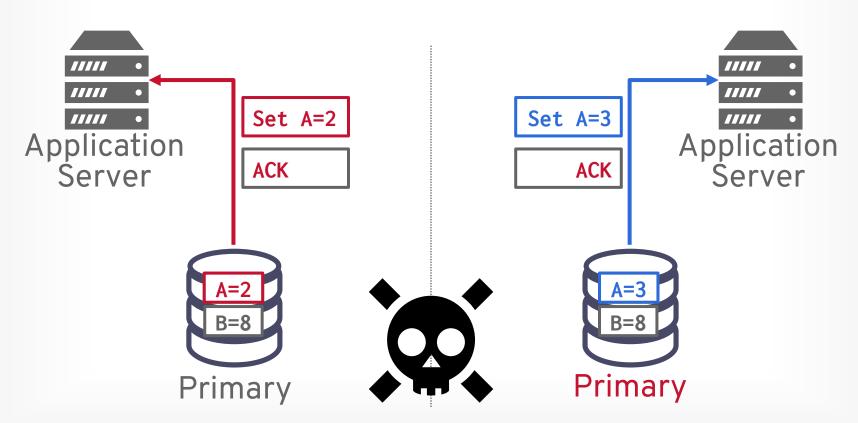




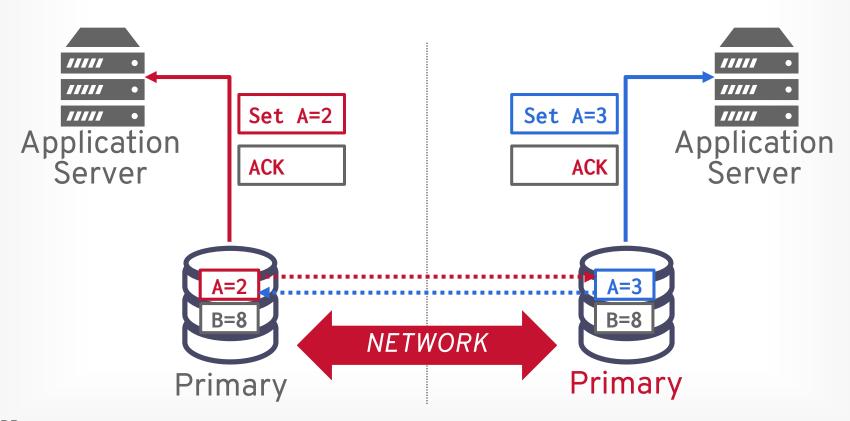














Choice #1: Halt the System

→ Stop accepting updates in any partition that does not have a majority of the nodes.

Choice #2: Allow Split, Reconcile Changes

- → Allow each side of partition to keep accepting updates.
- → Upon reconnection, perform reconciliation to determine the "correct" version of any updated record
- → Server-side: Last Update Wins
- → Client-side: <u>Vector Clocks</u>



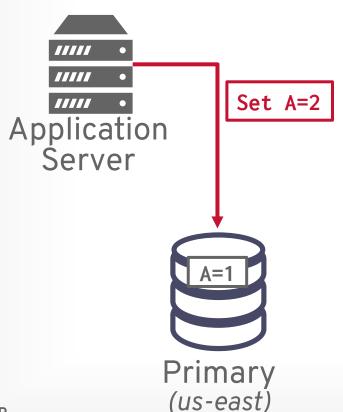


PACELC THEOREM

Extension to CAP <u>proposed in 2010</u> to include consistency vs. latency trade-offs:

- → Partition Tolerant
- \rightarrow **A**lways Available
- \rightarrow Consistent
- \rightarrow **E**lse, choose during normal operations
- $\rightarrow \underline{\mathbf{L}}$ atency
- \rightarrow **C**onsistency

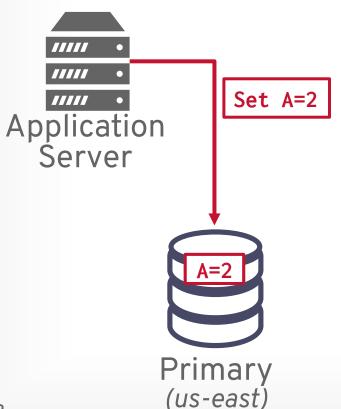








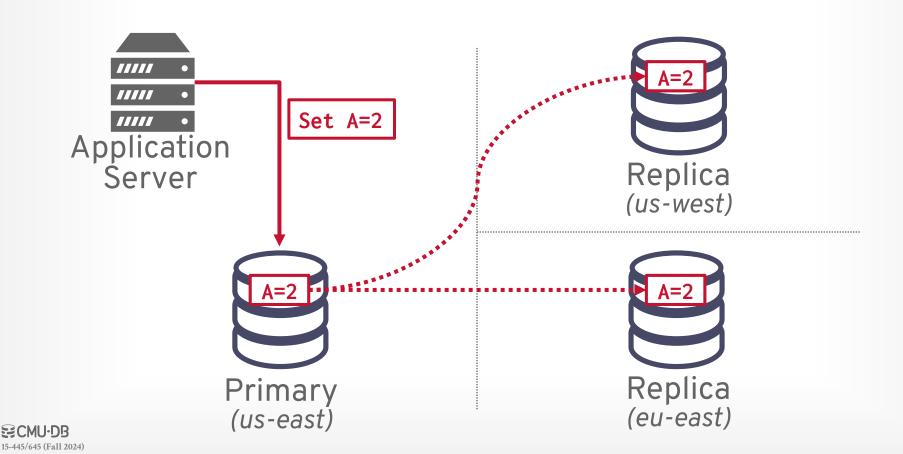


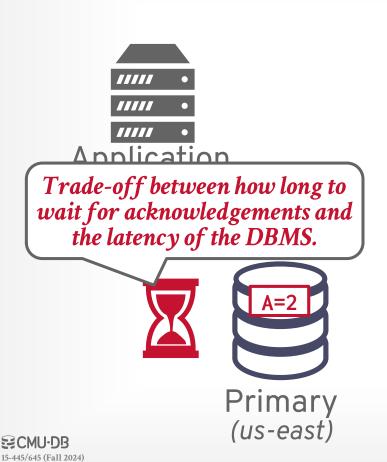


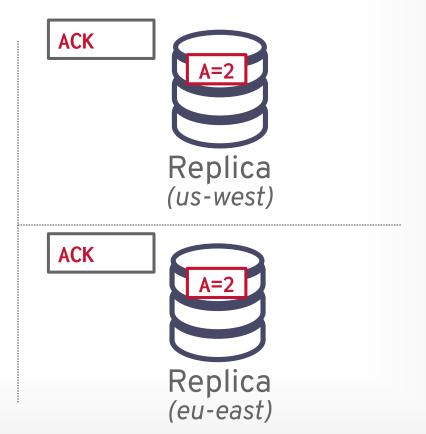


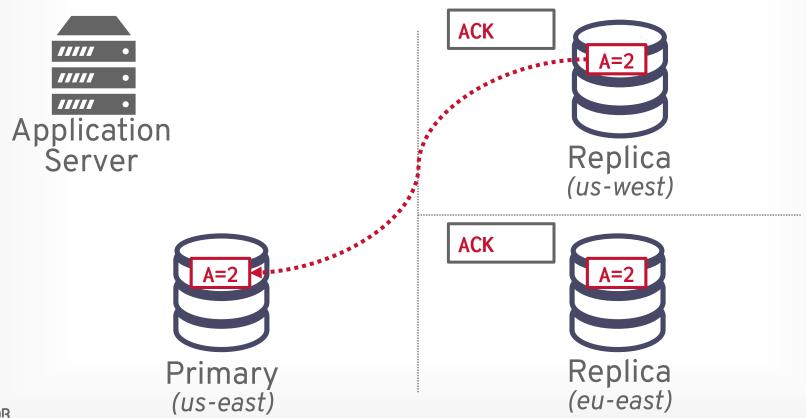




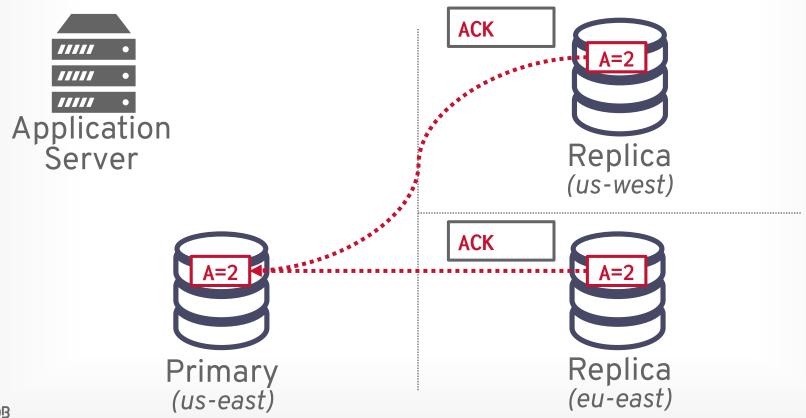




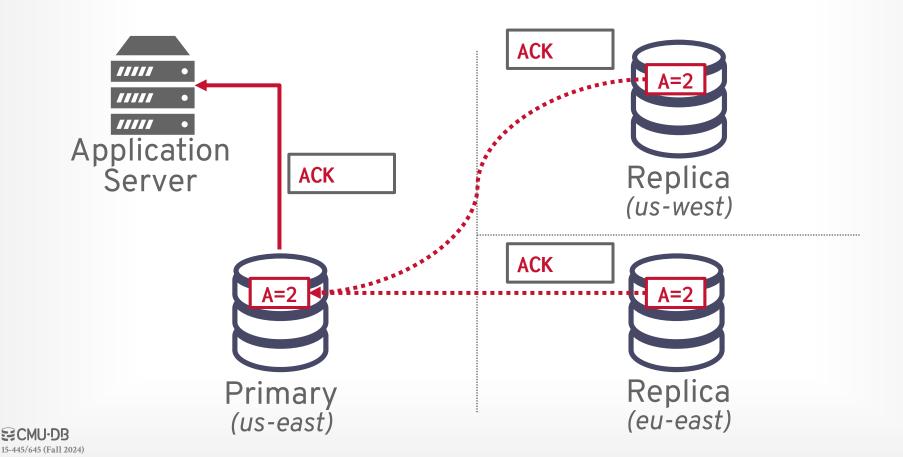












CONCLUSION

Maintaining transactional consistency across multiple nodes is hard. Bad things will happen.

2PC / Paxos / Raft are the most common protocols to ensure correctness in a distributed DBMS.

More info (and humiliation):

→ Kyle Kingsbury's Jepsen Project



NEXT CLASS

Distributed OLAP Systems

